

Mechanical Load in a Circular Rotating Disk With a Shaft for Different Materials Under Steady-State Temperature

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It has been observed that thermal effects increase the value of angular speed required to yield at the internal surface for incompressible/compressible materials. Radial stresses have a maximum value at the internal surface of the rotating disc made of incompressible materials as compared to compressible materials. With the introduction of thermal effects, radial as well as circumferential stresses must be decreased in the absence of mechanical load but when mechanical load is applied, radial as well as circumferential stresses must be increased at the internal surface of a rotating disc with a shaft. A rotating disc is likely to fracture at the bore of the radius.

Key words: load, stress, thermal stress, stress analysis, disc, rotating disc, yielding, elasticity and plasticity.

Nomenclature

a, b	- Inner and outer radii of the disc
ω	- Angular velocity of rotation
u, v, w	- displacement components
ρ	- Density of material
C	- Compressibility
T_{ij}, e_{ij}	- Stress and Strain rate tensor
Y	- Yield stress
T_0	- Load
E	- Young's modulus
λ, μ	- Lamé's constant
e_{kk}	- first strain invariant
δ_{ij}	- Kronecker's delta
P	- function of β
β	- function of r
k_1, k_2, K_1, K_2, d	- constants

Non dimensional quantities:

$R = r / b; R_0 = a / b$ - Radii ratio;
 $\sigma_0 = T_0 / Y$ - load;
 $\Omega^2 = \rho \omega^2 b^2 / Y$ - angular speed;
 $\sigma_r = T_{rr} / Y$ - Radial stress component;
 $\sigma_\theta = T_{\theta\theta} / Y$ - Circumferential stress component;
 $\Theta_1 = \alpha E \Theta_0 / Y$ - Temperature in Kelvin

Introduction

ROTATING disks subjected to mechanical and thermal loads have been studied in both linear and nonlinear forms. In the linear analysis, researchers mainly used the

infinitesimal elasticity theory [1] for the study of isotropic or anisotropic disks of uniform thickness profiles. In nonlinear cases, scientific literature mainly focused on three aspects, namely nonlinear geometry, material and analysis. Although many earlier studies on rotating disks [2] considered disks with uniform thickness, lately several authors [3-6] considered the nonlinear geometry of rotating disks, emphasizing the importance of variable thickness. Recent studies [7, 8] indicated that stresses in rotating disks (annular or solid) with variable thickness were much lower than those in uniform thickness disks at the same angular velocity. Unlike these studies where disks were subjected to mechanical loads only, many studies can be seen in the literature [9-13] with disks subjected to thermal load only. The accurate determination of stresses in rotating disks is important for an efficient design and material usage in engineering applications such as rotors of rotating machinery, flywheels, shrink fits, turbines, compressors, high speed gear engine and computer disc drives, etc. Pankaj Thakur [14] analyzed stresses in a thin rotating disc with inclusion and edge by using Seth's transition theory. The analysis of thin rotating discs made of isotropic materials has been discussed extensively by Timoshenko and Goodier [15] in the elastic range and by Chakrabarty [16] and Heyman [17] for the plastic range. Güven [18] discussed the problem with rigid inclusion under the assumptions of Tresca's yield condition, its associated flow rule and linear strain hardening. To obtain the stress distribution, Güven matched the plastic stresses at the same radius $r = z$ of the disc. Perfect elasticity and ideal plasticity are two extreme properties of the material and the use of an ad-hoc rule like yield condition amounts to divide the two extreme properties by a sharp line which is not physically possible. When a material passes from one state to another, a qualitatively different state transition takes place.

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Since this transition is non-linear in its character and difficult to investigate, researchers have taken certain ad-hoc assumptions like yield condition, incompressibility condition and a certain law which may or may not be valid for the problem. Seth's transition theory [19] does not require these assumptions and thus poses and solves a more general problem from which cases pertaining to the above assumptions can be worked out. This theory utilizes the concept of the generalized strain measure and an asymptotic solution at critical points or turning points of the differential equations defining the deformed field and it has been successfully applied to a large number of problems [6-14]. Seth [20] has defined the generalized principal strain measure as:

$$e_{ii} = \int_0^A \left[1 - 2e_{ii}^A \right]^{\frac{n}{2}-1} d e_{ii}^A = \frac{1}{n} \left[1 - \left(1 - 2e_{ii}^A \right)^{\frac{n}{2}} \right] \quad (1)$$

($i = 1, 2, 3$)

where n is the measure and e_{ii}^A is the principal Almansi finite strain components. For $n = -2, -1, 0, 1, 2$ it gives Cauchy, Green Hencky, Swainger and Almansi measures respectively.

The problem of analyzing mechanical load in a circular rotating disc with a shaft in a rotating annular disk mounted on a rigid circular shaft occurs frequently in industrial applications. In this paper, the plastic stresses have been derived by using Seth's transition theory. The results have been discussed numerically and depicted graphically.

Mathematical model

A thin annular disc of constant density with a central bore of the radius a and the outer radius b is considered. The disc, produced of material of constant density, is mounted on an edge loading. The disc is rotating with the angular speed ω about the central axis perpendicular to its plane. The disc thickness is assumed to be constant and is taken to be sufficiently small so that the disc is effectively in a state of plane stress, that is, the axial stress T_{zz} is zero. The temperature at the central bore of the disc is Θ .

Boundary conditions:

The rotating disc considered in the present study is subjected to a temperature gradient field and mechanical load. The inner surface of the disk is assumed to be fixed to a shaft so that isothermal conditions prevail on it. The outer surface of the disk is subjected to mechanical load and maintained at a uniform temperature gradient. Thus, the boundary conditions of the problem are given by:

$$r = a \quad u = 0; \quad r = b, \quad T_{rr} = T_0 \quad (2)$$

where u , T_{rr} and T_0 denote displacement, stress along the radial direction and load applied at the external surface.

Formulation of the Problem

The displacement components in the cylindrical polar co-ordinate are given by [20]:

$$u = r(1 - \beta), \quad v = 0, \quad w = dz \quad (3)$$

where β is the position function, depending on $r = \sqrt{x^2 + y^2}$ only, and d is a constant.

The finite strain components are given by Seth [20] as:

$$\begin{aligned} e_{rr}^A &= \frac{1}{2} [1 - (r\beta' + \beta)^2], \quad e_{\theta\theta}^A = \frac{1}{2} [1 - \beta^2], \\ e_{zz}^A &= \frac{1}{2} [1 - (1-d)^2], \quad e_{r\theta}^A = e_{\theta z}^A = e_{zr}^A = 0 \end{aligned} \quad (4)$$

where $\beta' = d\beta/dr$ and the meaning of the superscripts "A" is Almansi.

By substituting eq. (4) in eq. (1), the generalized components of strain become:

$$\begin{aligned} e_{rr} &= \frac{1}{n} [1 - (r\beta' + \beta)^n], \quad e_{r\theta} = e_{\theta z} = e_{zr} = 0 \\ e_{\theta\theta} &= \frac{1}{n} [1 - \beta^n], \quad e_{zz} = \frac{1}{n} [1 - (1-d)^n] \end{aligned} \quad (5)$$

The stress-strain relations for isotropic materials are given by [21]:

$$T_{ij} = \lambda \delta_{ij} I_1 + 2\mu e_{ij} - \xi \Theta \delta_{ij}, \quad (i, j = 1, 2, 3), \quad (6)$$

where T_{ij} is the stress components, λ and μ are Lamé's constants and $I_1 = e_{kk}$ is the first strain invariant, δ_{ij} is the Kronecker's delta and $\xi = \alpha(3\lambda + 2\mu)$, α being the coefficient of thermal expansion and Θ is the temperature. Further, Θ has to satisfy

$$\nabla^2 \Theta = 0 \Rightarrow \frac{d^2 \Theta}{dr^2} + \frac{1}{r} \frac{d\Theta}{dr} \equiv \frac{1}{r} \frac{d}{dr} \left(r \frac{d\Theta}{dr} \right) = 0 \quad \text{or} \quad \frac{d\Theta}{dr} = \frac{k}{r},$$

which has the solutions:

$$\Theta = k_1 (\log r + k_2) \quad (7)$$

where k_1 and k_2 are the constant of integration and can be determined from the boundary condition.

Equations (6) for this problem become:

$$\begin{aligned} T_{rr} &= \frac{2\lambda\mu}{\lambda + 2\mu} [e_{rr} + e_{\theta\theta}] + 2\mu e_{rr} - \frac{2\mu\xi\Theta}{(\lambda + 2\mu)}, \\ T_{\theta\theta} &= \frac{2\lambda\mu}{\lambda + 2\mu} [e_{rr} + e_{\theta\theta}] + 2e_{\theta\theta} - \frac{2\mu\xi\Theta}{(\lambda + 2\mu)}, \end{aligned} \quad (8)$$

$$T_{r\theta} = T_{\theta z} = T_{zr} = T_{zz} = 0$$

Substituting eq. (5) in eq. (8), the strain components in terms of stresses are obtained as [25]:

$$\begin{aligned} e_{rr} &= \frac{\partial u}{\partial r} - \frac{1}{2} \left(\frac{\partial u}{\partial r} \right)^2 = \frac{1}{2} [1 - (r\beta' + \beta)^2] = \\ &= \frac{1}{E} \left[T_{rr} - \left(\frac{1-C}{2-C} \right) T_{\theta\theta} \right] + \Theta \\ e_{\theta\theta} &= \frac{u}{r} - \frac{u^2}{2r^2} = \frac{1}{2} [1 - \beta^2] = \frac{1}{E} \left[T_{\theta\theta} - \left(\frac{1-C}{2-C} \right) T_{rr} \right] \\ e_{zz} &= \frac{\partial w}{\partial z} - \frac{1}{2} \left(\frac{\partial w}{\partial z} \right)^2 = \frac{1}{2} [1 - (1-d)^2] = \\ &= -\frac{(1-C)}{E(2-C)} [T_{rr} - T_{\theta\theta}], \\ e_{r\theta} &= e_{\theta z} = e_{zr} = 0 \end{aligned} \quad (9)$$

where E is the Young's modulus and C is the compressibility factor of the material. In term of Lamé's

constant, these are given by

$$E = \frac{\mu(3\lambda + 2\mu)}{(\lambda + \mu)}$$

and

$$C = \frac{2\mu}{\lambda + 2\mu}.$$

Substituting equation (5) in equation (8), one gets

$$T_{rr} = \frac{2\mu}{n} \left[3 - 2C - \beta^n \left\{ 1 - C + (2 - C)(P + 1)^n + \frac{nC\xi\Theta}{2\mu\beta^n} \right\} \right],$$

$$T_{\theta\theta} = \frac{2\mu}{n} \left[3 - 2C - \beta^n \left\{ 2 - C + (1 - C)(P + 1)^n + \frac{nC\xi\Theta}{2\mu\beta^n} \right\} \right],$$

$$T_{r\theta} = T_{\theta z} = T_{zr} = T_{zz} = 0, \quad (10)$$

where C is the compressibility factor of the material in term of Lamé's constant, given by $C = \frac{2\mu}{\lambda + 2\mu}$. Equations of equilibrium are all satisfied except

$$\frac{d}{dr}(rT_{rr}) - T_{\theta\theta} + \rho\omega^2 r^2 = 0, \quad (11)$$

where ρ is the density of the material of the rotating disc.

The temperature satisfies the Laplace equation (7) with the boundary condition $\Theta = \Theta_0$ at $r = a$, $\Theta = 0$ at $r = b$, where Θ_0 is constant, given by [21] $k_1 = \frac{\Theta}{\log(a/b)}$ and $k_2 = -\log b$. Substituting k_1 and k_2 from equation (7), one gets

$$\Theta = \frac{\Theta_0 \log(r/b)}{\log(a/b)}. \quad (12)$$

Using equations (10) and (12) in equation (11), one gets a non-linear differential equation in β as:

$$\begin{aligned} (2 - C)n\beta^{n+1}P(P + 1)^{n-1} \frac{dP}{d\beta} &= \\ &= \frac{n\rho\omega^2 r^2}{2\mu} - \frac{nC\xi\bar{\Theta}_0}{2\mu} + \\ &+ \beta^n \left[1 - (P + 1)^n - nP \left\{ \frac{1 - C}{2 - C} + (P + 1)^n \right\} \right] \end{aligned} \quad (13)$$

Where $\bar{\Theta}_0 = \frac{\Theta_0}{\log(a/b)}$ and $r\beta' = \beta P$ (P is a function of β and β is a function of r).

From equation (13), the turning points of β are $P = -1$ and $\pm\infty$.

Solution Through the Problem

For finding the plastic stress, the transition function is taken through the principal stress (see Seth [19, 20], Gupta et al. and Thakur [22, 42]) at the transition point $P \rightarrow \pm\infty$. The transition function Υ is defined as:

$$\begin{aligned} \Upsilon &= \left(\frac{n}{2\mu} \right) [T_{\theta\theta} - C\xi\Theta] = \\ &= \left[(3 - 2C) - \beta^n \left\{ 2 - C + (1 - C)(P + 1)^n \right\} - \frac{nC\xi\Theta}{\mu} \right] \end{aligned} \quad (14)$$

Taking the logarithmic differentiation of equation (14) with respect to r and using equation (13), one gets

$$\begin{aligned} \frac{d(\log \Upsilon)}{dr} &= \\ &= \left[\frac{\beta^n \left(\frac{1 - C}{2 - C} \right) \left[\frac{1 - (P + 1)^n - n(1 - C)P}{n\rho\omega^2 r^2 + \frac{nC\xi\bar{\Theta}_0(3 - 2C)}{2\mu\beta^n} + (2 - C)nP\beta^n} \right] + (2 - C)nP\beta^n}{r \left[3 - 2C - \beta^n \left\{ 2 - C + (1 - C)(P + 1)^n \right\} - \frac{nC\xi\Theta}{\mu} \right]} \right] \end{aligned} \quad (15)$$

Taking the asymptotic value of equation (15) at $P \rightarrow \pm\infty$ and integrating it, one gets

$$\Upsilon = K_1 r^{-1/(2-C)} \quad (16)$$

where K_1 is a constant of integration which can be determined by the boundary condition.

From equation (14) and (16), we have

$$T_{\theta\theta} = \left(\frac{2\mu}{n} \right) K_1 r^{-1/(2-C)} + \frac{C\xi\Theta_0 \ln(r/b)}{\ln(a/b)} \quad (17)$$

Substituting equation (17) in equation (11) and integrating it, one gets

$$\begin{aligned} T_{rr} &= \left\{ \frac{2\mu(2 - C)}{1 - C} \right\} K_1 r^{-1/(2-C)} + \frac{C\xi\Theta_0 \ln(r/b)}{\ln(a/b)} \\ &- \frac{C\xi\Theta_0}{\ln(a/b)} - \frac{\rho\omega^2 r^2}{3} + \frac{K_2}{r} \end{aligned} \quad (18)$$

where K_2 is a constant of integration, which can be determined by the boundary condition.

Substituting equations (17) and (18) in the second equation of (9), one gets

$$\beta = \sqrt{1 - \frac{2(1 - C)}{E(2 - C)} \left[\frac{\rho\omega^2 r^2}{3} - \frac{K_2}{r} + \frac{\alpha E\Theta_0(2 - C)}{\ln(a/b)} \right] \left[1 + \frac{2}{(1 - C)} \ln(r/b) \right]} \quad (19)$$

Substituting equation (19) in equation (3), one gets

$$u = r - r \sqrt{1 - \frac{2\nu}{E} \left[\frac{\rho\omega^2 r^2}{3} - \frac{K_2}{r} + \frac{\alpha E\Theta_0(2 - C)}{\ln(a/b)} \right] \left[1 + \frac{2}{(1 - C)} \ln(r/b) \right]} \quad (20)$$

where $E = \frac{2\mu(3 - 2C)}{(2 - C)}$ is the Young's modulus and is

$\nu = \frac{1 - C}{2 - C}$ Poisson's ratio in terms of a compressibility factor. Using the boundary condition (3) in equations (18) and (20), one gets

$$K_1 = \frac{n\nu}{2\mu b^\nu} \left[bT_0 + \frac{\rho\omega^2(b^3 - a^3)}{3} \right] + \frac{\alpha E\Theta_0(1-C)(b-a)}{2\mu \ln(a/b)b^\nu} - \frac{\alpha E\Theta_0 na}{\mu b^\nu}$$

and

$$K_2 = \frac{\rho\omega^2 a^3}{3} + \frac{\alpha E\Theta_0(2-C)}{\ln(a/b)} \left[1 - \frac{2}{(1-C)} \ln\left(\frac{r}{b}\right) \right].$$

Substituting the values of the constants K_1 and K_2 from equations (17), (18), and (20), respectively, one gets the transitional stresses and displacement as:

$$T_{\theta\theta} = \left\{ \begin{aligned} & \frac{\rho\omega^2(b^3 - a^3)\nu}{3r} \left(\frac{r}{b}\right)^\nu + \nu T_0 \left(\frac{r}{b}\right)^{\nu-1} - 2\alpha E\Theta_0 \left(\frac{a}{r}\right) \left(\frac{r}{b}\right)^\nu \\ & + \alpha E\Theta_0(2-C) \left[\frac{(1-C)(b-a)}{r(2-C)\ln(a/b)} \left(\frac{r}{b}\right)^\nu - \frac{\ln(r/b)}{\ln(a/b)} \right] \end{aligned} \right\} \quad (21)$$

$$T_{rr} = \left\{ \begin{aligned} & \frac{\rho\omega^2}{3r} \left[\left(\frac{r}{b}\right)^\nu (b^3 - a^3) - r^3 + a^3 \right] + \left(\frac{r}{b}\right)^{\nu-1} T_0 \\ & + \frac{2\alpha E\Theta_0}{\nu} \left[\frac{a}{r} - \frac{a}{r} \left(\frac{r}{b}\right)^\nu \right] \\ & + \frac{\alpha E\Theta_0(2-C)}{\ln(a/b)} \left[\ln(r/b) + \frac{(b-a)}{r} \left(\frac{r}{b}\right)^\nu + \frac{a}{r} - 1 \right] \end{aligned} \right\} \quad (22)$$

$$u = r - r \sqrt{1 - \frac{2\nu}{E} \left[\frac{\rho\omega^2(r^3 - a^3)}{3r} + \frac{\alpha E\Theta_0(2-C)(r-a)}{r \ln(a/b)} + \frac{2(2-C)\alpha E\Theta_0}{(1-C)} \left[\frac{\ln(r/b)}{\ln(a/b)} - \frac{a}{r} \right] \right]} \quad (23)$$

$$|T_{rr} - T_{\theta\theta}| = \left| \begin{aligned} & \frac{\rho\omega^2}{3r} \left[\left(\frac{r}{b}\right)^\nu (b^3 - a^3)(1-\nu) - r^3 + a^3 \right] + \left(\frac{r}{b}\right)^{\nu-1} (1-\nu) T_0 \\ & + \alpha E\Theta_0 \left[\frac{2\left(\frac{a}{r}\right)\frac{1}{\nu} - \frac{2a}{(1-C)r} \left(\frac{r}{b}\right)^\nu}{\frac{(b-a)}{r \ln(a/b)} \left(\frac{r}{b}\right)^\nu} + \frac{1}{\log(a/b)(1-\nu)} \left(\frac{a-r}{r}\right) \right] \end{aligned} \right| \quad (24)$$

Initial yielding: It is seen from Fig.2 that $|T_{rr} - T_{\theta\theta}|$ is maximum at the internal surface (i.e. at $r = a$); therefore, yielding will take place at the internal surface of the disc and equation (24) gives:

$$|T_{rr} - T_{\theta\theta}|_{r=a} = \left| \begin{aligned} & \frac{\rho\omega^2(b^3 - a^3)(1-\nu)}{3a} \left(\frac{a}{b}\right)^\nu + \left(\frac{a}{b}\right)^{\nu-1} (1-\nu) T_0 \\ & + \alpha E\Theta_0 \left[\frac{(b-a)}{a \ln(a/b)} \left(\frac{a}{b}\right)^\nu - \frac{2}{(1-C)} \left(\frac{a}{b}\right)^\nu + \frac{2}{\nu} \right] \end{aligned} \right| \quad (2)$$

= $Y(\text{say})$

5)

where Y is yielding stresses. And the angular speed necessary for the initial yielding is given from equation (25):

$$\Omega_i^2 = \frac{\rho\omega_i^2 b^2}{Y} = \left| \begin{aligned} & \frac{3ab^2 \left[1 - \left(\frac{T_0}{Y}\right) (1-\nu) \left(\frac{a}{b}\right)^{\nu-1} \right]}{\left(\frac{a}{b}\right)^\nu (b^3 - a^3)(1-\nu)} \\ & - \left[\frac{3}{(1-\nu)(1-a^3/b^3)} \right] \left(\frac{\alpha E\Theta_0}{Y} \right) \\ & - \left[\frac{(1-a/b)}{\ln(a/b)} - \frac{2}{\nu} (1-\nu) \left(\frac{a}{b}\right) + \frac{2}{\nu} \left(\frac{a}{b}\right)^{1-\nu} \right] \end{aligned} \right| \quad (26)$$

where $1-C = (1-\nu)/\nu$, $\sigma_0 = T_0/Y$ and $\omega_i = \frac{\Omega_i}{b} \sqrt{Y/\rho}$.

We introduce the following non-dimensional components: $R = r/b$, $R_0 = a/b$, $\sigma_r = T_{rr}/Y$, $\sigma_\theta = T_{\theta\theta}/Y$, $U = u/b$, $\Theta_1 = \alpha E\Theta_0/Y$, $\Omega^2 = \rho\omega^2 b^2/Y$, $\sigma_0 = T_0/Y$ and $H = Y/E$. Thermo elastic-plastic transitional stresses, displacement and angular speed from equations (21)-(23) and (26) in a non-dimensional form become:

$$\sigma_\theta = \frac{\Omega_i^2}{3R} \nu (1-R_0^3) R^\nu + \nu R^{\nu-1} \sigma_0 + \frac{\Theta_1}{1-\nu} \left[\frac{(1-R_0)\nu}{R \ln R_0} R^\nu + \frac{\ln R}{\ln R_0} - 2R_0(1-\nu) R^{\nu-1} \right] \quad (27)$$

$$\sigma_r = \left\{ \begin{aligned} & \sigma_0 R^{\nu-1} + \frac{\Omega_i^2}{3R} \left[R^\nu (1-R_0^3) - R^3 + R_0^3 \right] \\ & + \frac{2\Theta_1}{\nu} \left[\frac{R_0}{R} - \frac{R_0}{R} R^\nu \right] \\ & + \frac{\Theta_1}{(1-\nu) \ln R_0} \left[\ln R + \frac{(1-R_0)}{R} R^\nu + \frac{R_0}{R} - 1 \right] \end{aligned} \right\} \quad (28)$$

$$U = R - R \left\{ 1 - 2\nu H \left[\frac{\Omega_i^2}{3R} (R^3 - R_0^3) + \frac{2\Theta_1(R-R_0)}{R \ln R_0 (1-\nu)} + \frac{2\Theta_1}{\nu} \left[\frac{\ln R}{\ln R_0} - \frac{R_0}{R} \right] \right] \right\}^{1/2} \quad (29)$$

and

$$\Omega_i^2 = \left| \begin{aligned} & \frac{3}{(1-R_0^3)(1-\nu)} R_0^{\nu-1} - \frac{3\sigma_0}{(1-R_0^3)} \\ & - \left[\frac{3\Theta_1}{(1-\nu)(1-R_0^3)} \right] \left[\frac{(1-R_0)}{\ln R_0} - \frac{2}{\nu} R_0^{1-\nu} + \frac{2(1-\nu)}{\nu} R_0 \right] \end{aligned} \right| \quad (30)$$

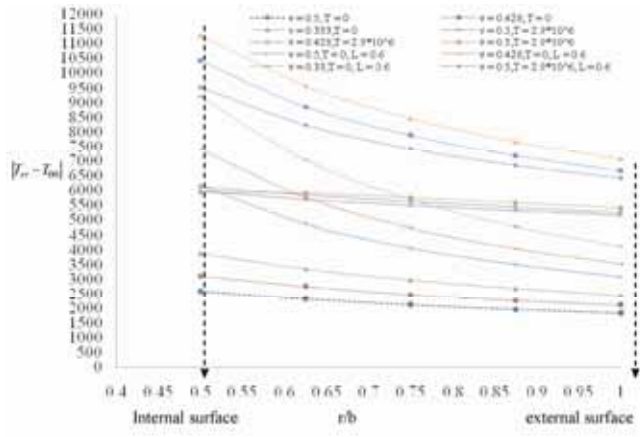


Figure 1. Graph between $|T_{rr} - T_{\theta\theta}|$ and r/b .

Fully plastic state: The angular speed of the rotating disc becomes fully plastic ($\nu \rightarrow 1/2 = 0.5$) at the external surface and eq. (24) becomes:

$$\begin{aligned} |T_{rr} - T_{\theta\theta}|_{r=b} &= \left| \frac{1}{2} T_0 - \frac{\rho \omega_f^2 (b^3 - a^3)}{6b} + \alpha E \Theta_0 \left[\frac{(b-a)}{b \ln(a/b)} - 2 \left(\frac{a}{b} \right) \right] \right| \quad (31) \\ &\equiv Y^* (\text{say}) \end{aligned}$$

where Y^* is yielding stresses which occur for the fully plastic state. The angular speed required for the disc to become fully plastic is given by equation (31):

$$\begin{aligned} \Omega_f^2 = \frac{\rho \omega_f^2 b^2}{Y^*} &= \left| \frac{6}{1 - (a^3/b^3)} \cdot \left(\frac{\sigma_0}{2} - 1 \right) \right| \quad (32) \\ &- \left| \frac{6}{1 - (a^3/b^3)} \left(\frac{\alpha E \Theta}{Y^*} \right) \left[\frac{(1-a/b)}{\ln(a/b)} - 2 \left(\frac{a}{b} \right) \right] \right| \end{aligned}$$

where $\sigma_0^* = T_0 / Y^*$ and $\omega_f = \frac{\Omega_f}{b} \sqrt{Y^* / \rho}$.

Stresses, displacement and the angular speed for the fully plastic state ($\nu \rightarrow 1/2 = 0.5$) are obtained from eqs. (27)-(29) and eq. (32) as:

$$\begin{aligned} \sigma_\theta &= \frac{1}{2\sqrt{R}} \left[\sigma_0 + \frac{\Omega_f^2}{3} (1 - R_0^3) \right] + \quad (33) \\ &2\Theta_1 \left[\frac{(1-R_0)}{2R \ln R_0} R^{1/2} + \frac{\ln R}{\ln R_0} - \frac{R_0}{\sqrt{R}} \right] \end{aligned}$$

$$\sigma_r = \left\{ \begin{aligned} &\frac{\sigma_0}{\sqrt{R}} + \frac{\Omega_f^2}{3R} \left[\sqrt{R} (1 - R_0^3) - R^3 + R_0^3 \right] \\ &+ 4\Theta_1 \left[\frac{R_0}{R} - \frac{R_0}{\sqrt{R}} \right] \\ &+ \frac{2\Theta_1}{\ln R_0} \left[\ln R + \frac{(1-R_0)}{R} R^{1/2} + \frac{R}{R_0} - 1 \right] \end{aligned} \right\} \quad (34)$$

$$U = R - R \left\{ 1 - H \left[\frac{\Omega_f^2 (R^3 - R_0^3) + \frac{4\Theta_1 (R - R_0)}{R \ln R_0}}{+ 4\Theta_1 \left[\frac{\ln R}{\ln R_0} - \frac{R_0}{R} \right]} \right]^{1/2} \right\} \quad (35)$$

$$\Omega_f^2 = \left| \frac{6}{(1 - R_0^3)} \cdot \left(\frac{\sigma_0}{2} - 1 \right) \right| - \left| \frac{6\Theta_1}{(1 - R_0^3)} \left[\frac{(1 - R_0)}{\ln R_0} - 2R_0 \right] \right| \quad (36)$$

Numerical Illustration and Discussion

Hasan Callioglu *et al.* [43] analyzed the problems of the stress analysis of functional graded material discs under mechanical and thermal loads. After that, Nitin Chandel *et al.* [44] investigated the thermo-elastic behavior of a thin circular Functionally Graded Material (FGM) Disk subjected to thermal loads. But in this paper we discuss an isotropic material circular disc subjected to mechanical loads and thermal effects by using Seth's theory.

For calculating the thermal stresses, the angular speed and the displacement based on the above analysis, the following values have been taken numerically: $\nu = 0.5$ (incompressible material *e.g.* rubber material), 0.42857 (compressible material *e.g.* gold), 0.333 (compressible material *e.g.* copper or brass material), $E/Y = 2$ and $1/2$, $\Theta_0 = 0$ and 5811 K , $\alpha = 255 \text{ K}$ (for methyl methacrylate) [45], respectively. The curves have been drawn in Fig. 2 between the angular speed Ω_f^2 required for the initial yielding and various radii ratios $R_0 = a/b$ for $\nu = 0.5$, 0.4285, 0.333, $L = \sigma_0 = 0, 0.3, 0.6$ and different values of the temperature $\Theta_1 = 0, 2.9 \times 10^6$.

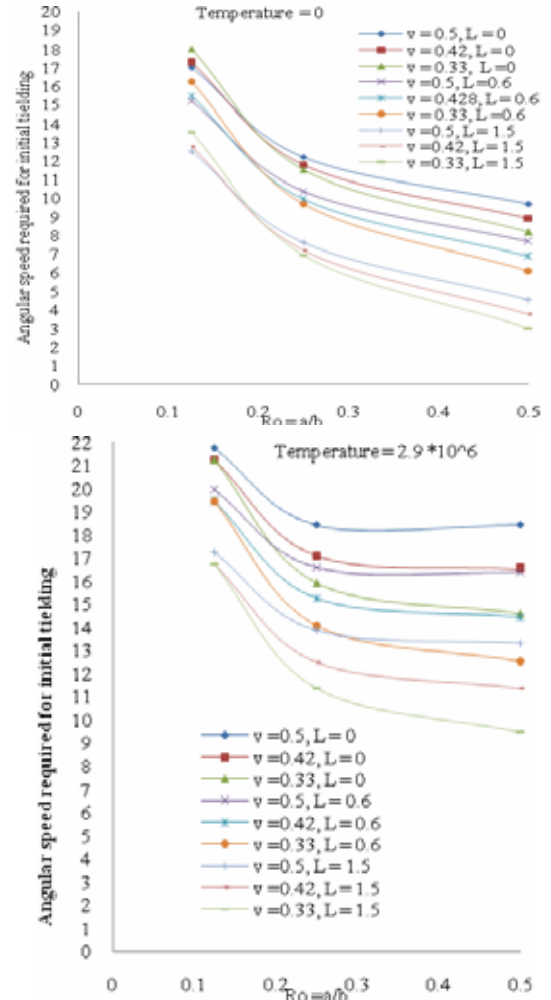


Figure 2. Angular speed required for the initial yielding at the internal surface of the rotating disc with a shaft for $\nu = 0.5, 0.428, 0.333$ and different values of load ($L = 0, 0.3, 0.6$) along the radii $R_0 = a/b$.

It has been observed that, in the absence of mechanical load, a rotating disc with a shaft required much higher angular speed for incompressible materials (e.g. rubber) as compared to compressible materials (e.g. copper or gold). Mechanical load for rotating discs decreases the angular speed value for incompressible as well as compressible materials.

With the introduction of thermal effect increase, the angular speed value is required to yield at the internal surface for incompressible/compressible materials. In Figures 3 and 4, the curves have been drawn for the thermal stresses distribution and the displacement with respect to the radius $R = r/b$ for the elastic-plastic transitional state and the fully plastic state, respectively. From Figures 3 and 4, it has been seen that the radial stresses have the maximum value at the internal surface of the rotating disc made of incompressible material as compared to that made of compressible material. With the introduction of a thermal effect, radial as well as circumferential stresses must be decreased in the absence of mechanical load but when mechanical load is applied, the applied radial as well as circumferential stresses must be increased at the internal surface of the rotating disc with a shaft. The rotating disc is likely to fracture by cleavage close to the inclusion at the bore.

Conclusion:

It has been observed that thermal effects increase the value of the angular speed required to yield at the internal surface for incompressible/compressible materials. Radial stresses have the maximum value at the internal surface of rotating discs made of incompressible materials as compared to those made of compressible materials. With the introduction of thermal effects, radial as well as circumferential stresses must be decreased in the absence of mechanical load but when mechanical load is applied, the applied radial as well as circumferential stresses must be increased at the internal surface of the rotating disc with inclusion.

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Mehaničko opterećenje u kružno obrtnom disku sa osovinom za različite materijale pri stabilnoj temperaturi

Uočeno je da uvođenje termičkog efekta povećava zahtevanu vrednost ugaone brzine za tečenje na unutrašnjoj površini za nestišljive/stišljive materijale. Radijalni naponi imaju maksimalnu vrednost na unutrašnjoj površini obrtnog diska izrađenog od nestišljivog materijala u poređenju sa stišljivim materijalom. Radijalni naponi imaju maksimalnu vrednost na unutrašnjoj površini obrtnog diska izrađenog od nestišljivog materijala u poređenju sa stišljivim materijalom. Sa uvođenjem termičkog efekta radijalni isto kao i tangencijalni naponi moraju se smanjiti kada nema mehaničkog opterećenja, ali kada deluje mehaničko opterećenje tada se radijalni kao i tangencijalni naponi moraju povećati na unutrašnjoj površini obrtnog diska s osovinom. Lom obrtnog diska je verovatan u blizini centralnog otvora.

Ključne reči: opterećenje, naponsko stanje, termičko opterećenje, analiza napona, disk, rotacioni disk, tečenje materijala, elastičnost.

Механические напряжения в круглых вращающихся дисках с валом для различных материалов при постоянной температуре

Было отмечено, что введение теплового эффекта увеличивает требуемое значение угловой скорости потока на внутренней поверхности для несжимаемых / сжимаемых материалов. Радиальные усилия имеют максимальное значение на внутренней поверхности вращающегося диска, изготовленного из несжимаемого материала по сравнению с сжимаемым материалом. Со введением теплового эффекта должны быть уменьшены радиальные напряжения, а также и касательные напряжения, если нет механических напряжений, но когда действуют механические нагрузки, то и радиальные и касательные напряжения необходимо увеличить на внутреннюю поверхность вращающегося диска с валом. Лом вращающегося диска, скорее всего и чаще всего происходит рядом с центральным отверстием.

Ключевые слова: нагрузка, напряжённое состояние, тепловая нагрузка, анализ напряжений, диск, вращающийся диск, поток материала, упругая пластичность.

Charge mécanique dans le disque rotatif circulaire avec l'axe pour les différents matériaux à température stable

On a constaté que l'introduction de l'effet thermique augmentait la valeur exigée de la vitesse d'angle pour le cédage sur la surface intérieure chez les matériaux incompressibles / compressibles. Les tensions radiales ont la valeur maximale sur la surface intérieure du disque rotatif qui est produit en matériau incompressible en comparaison avec le matériau compressible. Avec l'introduction de l'effet thermique les tensions radiales ainsi que celles tangentielles doivent décroître quant il n'y a pas de charge mécanique mais quand la charge mécanique est appliquée les tensions radiales et tangentielles doivent augmenter sur la surface intérieure du disque rotatif avec l'axe. La fracture du disque rotatif est probable à proximité de l'ouverture centrale.

Mots clés: charge, état de tension, charge thermique, analyse de tension, disque, disque rotatif, cédage du matériau, élasticité plastique.